

Math 275 Elementary Differential Equations

Chapter 1

1.1 Examples

Definitions

An equation containing the derivatives or differentials of one or more dependent variables, with respect to one or more independent variables, is called a **differential equation** (DE). A variable is called an **independent variable** when an equation contains one or more derivatives with respect to the variable; a variable is called a **dependent variable** if a derivative of this variable occurs.

Examples

$$1. \quad x \frac{dy}{dx} + y^2 = 0$$

x – independent variable

y – dependent variable

The DE can also be written as

$$x + y^2 \frac{dx}{dy} = 0$$

x – dependent variable

y – independent variable

$$2. \quad L \frac{di}{dt} + Ri = E$$

i – dependent variable

t – independent variable

L , R , and E – **parameters**

$$3. \quad x \frac{\delta u}{\delta x} = - \frac{\delta v}{\delta y}$$

x , y – independent variables

u , v – dependent variables

1.2 Definitions

There are **three ways** to classify DE:

By (1) type

(2) order

(3) linearity

Classification by Type

(a) **ordinary differential equation** (ODE)

- an equation containing only derivatives of one or more dependent variables, with respect to a single independent variable

Examples:

$$\frac{dy}{dx} - 4y = 1$$

$$\frac{dy}{dx} = \sin x$$

$$\frac{du}{dx} + \frac{dv}{dx} = x$$

$$\frac{d^2y}{dx^2} - 2\frac{dy}{dx} + 6y = 0$$

(b) partial differential equation (PDE)

- an equation involving the derivatives of one or more dependent variables of two or more independent variables

Examples:

$$\frac{\delta u}{\delta x} = -\frac{\delta v}{\delta y}$$

$$x\frac{\delta u}{\delta x} + y\frac{\delta u}{\delta y} = u$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial t^2} - 2\frac{\delta u}{\delta t}$$

Classification by Order

Definition The **order** of a differential equation is the order of the highest-ordered derivative appearing in the equation.

The equation

$$F(x, y, y', \dots, y^{(n)}) = 0 \quad (1)$$

is called an “ n th order” ordinary differential equation.

We shall assume that it is always possible to solve for $y^{(n)}$ in terms of the other $n + 1$ variables $x, y, y', \dots, y^{(n-1)}$, i.e.

$$y^{(n)} = f(x, y, y', \dots, y^{(n-1)}). \quad (2)$$

Examples

1. $\underbrace{\frac{d^2w}{dx^2}}_{2nd \text{ order}} - x \underbrace{\left(\frac{dw}{dx}\right)^4}_{1st \text{ order}} - 4w = e^{2x} \Rightarrow$ DE is of order 2 or DE is a second-order equation
2. $\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0$ is a second-order PDE

Classification by Linearity

Definition An ordinary differential equation of order n is called **linear** if it may be written in the form

$$b_0(x) \frac{d^n y}{dx^n} + b_1(x) \frac{d^{n-1} y}{dx^{n-1}} + \dots + b_{n-1}(x) \frac{dy}{dx} + b_n(x) y = R(x).$$

The notion of linearity may be extended to partial differential equations.

Note: Linear DE are characterized by two properties:

- (i) The dependent variable y and all its derivatives are of the first degree, i.e. the power of each term involving y is 1.
- (ii) Each coefficient depends only on the variable x .

Definition An equation that is not linear is said to be **nonlinear**.

Examples

$$x dy + y dx = 0$$

$$y'' - 2y' + y = 0$$

$$x^3 \frac{d^3 y}{dx^3} + x^2 \frac{d^2 y}{dx^2} - 3x \frac{dy}{dx} + 5y = e^x$$

are all linear DE, but

$$yy'' - 2x \left(\frac{d^3 y}{dx^3} \right)^2 + y^3 = 0 \text{ is nonlinear.}$$

Solution of a DE

Definition A function ϕ defined on an interval $a < x < b$, is called a **solution** of the differential equation (2), provided that the n derivatives of the function exist on the interval $a < x < b$ and

$$\phi^{(n)}(x) = f(x, \phi(x), \phi'(x), \dots, \phi^{(n-1)}(x)),$$

for every x in $a < x < b$.

Example 3 Show that $y = xe^x$ is a solution of the linear equation $y'' - 2y' + y = 0$ on $(-\infty, \infty)$.

Solution:

$$\left. \begin{array}{l} y = xe^x \\ y' = xe^x + e^x \\ y'' = xe^x + 2e^x \end{array} \right\} \Rightarrow y'' - 2y' + y = xe^x + 2e^x - 2xe^x - 2e^x + xe^x = 0$$

Note:

1. The constant function $y = 0$, $-\infty < x < \infty$, also satisfies the DE. This solution is called the **trivial solution**.
2. Not every DE necessarily has a solution.

Example 4 The first-order DE $\left(\frac{dy}{dx}\right)^2 + 1 = 0$ and $(y')^2 + y^2 + 4 = 0$ do not have real solutions. Why?

Example 5 The second-order DE $(y'')^2 + 10y^4 = 0$ has only one real solution. What is it?

1.3 Families of Solutions

Definition A given DE usually possesses an infinite number of solutions, called a **family of solutions**.

In calculus, solutions of the first-order DE

$$\frac{dy}{dx} = f(x) \quad (1)$$

are given by

$$y = \int f(x) dx + c, \quad (2)$$

where c is an arbitrary constant. (2) is called a **one-parameter family** of solutions to (1), with c as the **parameter**.

Example 1 The DE

$$\frac{dy}{dx} = 2 \cos 3x$$

has the family of solutions

$$y = \frac{2}{3} \sin 3x + c.$$

Example 2 Show that the function $y = c_1 \cos 4x + c_2 \sin 4x$, where c_1 and c_2 are arbitrary constants, is a solution of the DE $y'' + 16y = 0$.

Solution:

$$\left. \begin{array}{l} y = c_1 \cos 4x + c_2 \sin 4x \\ y' = -4c_1 \sin 4x + 4c_2 \cos 4x \\ y'' = -16c_1 \cos 4x - 16c_2 \sin 4x \end{array} \right\} \Rightarrow y'' + 16y = -16c_1 \cos 4x - 16c_2 \sin 4x + 16c_1 \cos 4x + 16c_2 \sin 4x = 0$$

$y = c_1 \cos 4x + c_2 \sin 4x$ is a **two-parameter** family of solutions to the DE $y'' + 16y = 0$.

Note: When solving an n th-order DE $F(x, y, y', \dots, y^{(n)}) = 0$ we expect an **n-parameter family of solutions** $G(x, y, c_1, \dots, c_n) = 0$.

Definition A solution of a DE that is free of arbitrary parameters is called a **particular solution**.

One way of obtaining a particular solution is to choose specific values of the parameter(s).

Definition A DE along with subsidiary conditions on the unknown function and its derivatives, all given at the same value of the independent variable, constitutes an **initial-value problem** (IVP). The subsidiary conditions are **initial conditions**. If the subsidiary conditions are given at more than one value of the independent variable, the problem is a **boundary-value problem** (BVP) and the conditions are **boundary conditions**.

Example 3 $y'' + 2y' = e^x$; $y(\pi) = 1$, $y'(\pi) = 2$ is an IVP.

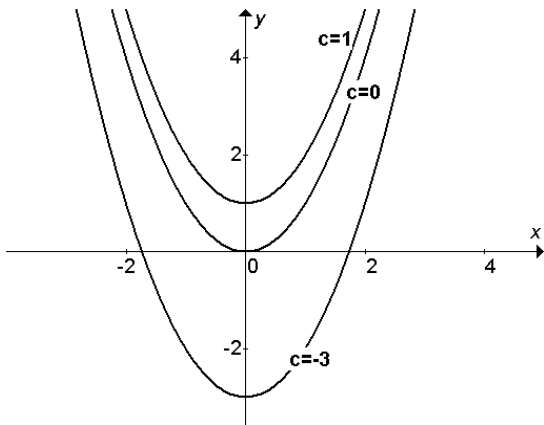
Example 4 $y'' + 2y' = e^x$; $y(0) = 1$, $y(1) = 1$ is a BVP.

A solution to an IVP or BVP is a function that both solves the DE and satisfies all the given subsidiary conditions.

1.4 Geometric Interpretation

Solutions to a DE graph as a family of parallel curves.

Example 1 $\frac{dy}{dx} = 2x$ 1st-order DE
 $y = x^2 + c$ solutions

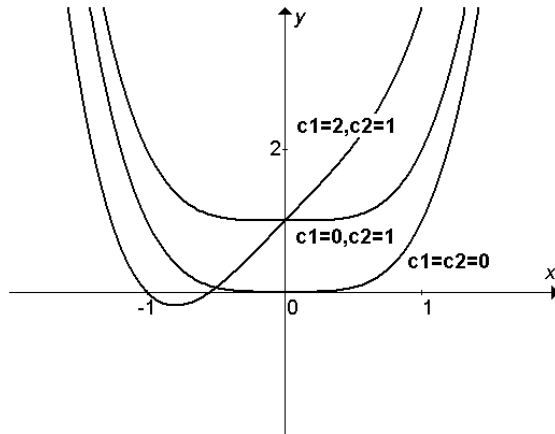


Note: Through each point in the plane there passes one and only one member of the family of solutions. We assume this is true for any first-order DE.

Example 2 (Ex 1.7 p 11)

$y'' = 12x^2$ 2nd-order DE

$y = x^4 + c_1x + c_2$ family of solutions



Note: There are at least 2 solutions passing through $(0,1)$ and a point near $(-1/2,0)$. However these pairs of solutions do not have the same slope at their point of intersection. Thus, for second-order equations we have:

Through each point in the plane there passes one and only one member of the family of solutions that has a given slope.

1.5 The Isoclines of an Equation

Consider the first-order DE

$$\frac{dy}{dx} = f(x, y). \quad (1)$$

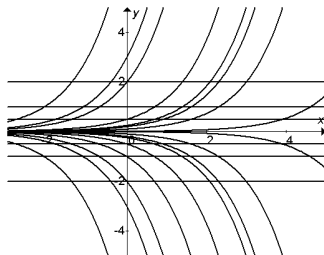
(1) assigns to each point $(a, b) \in D_f$ some direction or slope $f(a, b)$ and we can talk of the **direction field** or **slope field** of a DE.

A useful direction field can be constructed by evaluating f at each point of a rectangular grid consisting of at least a few hundred points. Then, at each point of the grid, a short line segment is drawn whose slope is the value of f at each point. This can be done systematically by first drawing curves called **isoclines**, i.e. curves along which the direction indicated by (1) is fixed.

Example 1 (Ex 1.8 p 12)

$$\frac{dy}{dx} = y$$

Isoclines are straight lines $f(x, y) = y = c$.



1.6 An Existence Theorem

Consider the initial value problem:

$$\text{Solve } \frac{dy}{dx} = f(x, y) \quad (1)$$

$$\text{s.t. } y(x_0) = y_0.$$

Let T denote the rectangular region defined by

$$|x - x_0| \leq a \quad \text{and} \quad |y - y_0| \leq b,$$

a region with the point (x_0, y_0) at its center. Suppose that f and $\partial f/\partial y$ are continuous functions of x and y in T .

Under the conditions imposed on $f(x, y)$, an interval exists about x_0 , $|x - x_0| \leq h$, and a function $y(x)$ which has the properties:

- (a) $y = y(x)$ is a solution of equation (1) on the interval $|x - x_0| \leq h$.
- (b) On the interval $|x - x_0| \leq h$, $y(x)$ satisfies the inequality

$$|y(x) - y(x_0)| \leq b.$$

- (c) At $x = x_0$, $y = y(x_0) = y_0$.

- (d) $y(x)$ is unique on the interval $|x - x_0| \leq h$ in the sense that it is the only function that has all the properties (a), (b), and (c).

The interval $|x - x_0| \leq h$ may or may not need to be smaller than the interval $|x - x_0| \leq a$ over which conditions were imposed upon $f(x, y)$.

Roughly, the theorem says that if $f(x, y)$ is sufficiently well behaved near the point (x_0, y_0) , then the differential equation (1) has a solution that passes through the point (x_0, y_0) and that solution is unique near (x_0, y_0) .

Existence of a Unique Solution

Let R be a rectangular region in the xy -plane defined by $a \leq x \leq b$, $c \leq y \leq d$ that contains the point (x_0, y_0) in its interior. If $f(x, y)$ and $\partial f/\partial y$ are continuous on R , then there exists some interval I_0 $x_0 - h < x < x_0 + h$, $h > 0$, contained in $a \leq x \leq b$, and a unique function $y(x)$, defined on I_0 , that is a solution of the IVP

$$\frac{dy}{dx} = f(x, y)$$

$$\text{s.t. } y(x_0) = y_0.$$