

1. Mark the following as TRUE or FALSE.
  - a. Homogeneous systems are always consistent.
  - b. If  $A$  and  $B$  are  $n \times n$  matrices with no zero entries, then  $AB \neq O$ .
  - c. The sum of two symmetric matrices is symmetric.
  - d.  $A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$  defines a matrix transformation that reflects the vector  $\begin{bmatrix} x \\ y \end{bmatrix}$  about the  $x$ -axis.
  - e. Every matrix in row echelon form is also in reduced row echelon form.
  - f. Any matrix equivalent to an identity matrix is nonsingular.
  - g. If  $B$  is the reduced row echelon form of  $A$ , then  $\det(B) = \det(A)$ .
  - h. If  $\det(A) = 0$ , then  $A$  has at least two equal rows.
  - i.  $\det(AB^T A^{-1}) = \det(B)$
  - j. The determinant of an elementary matrix is always equal to 1.

$$2. \text{ Let } A = \begin{bmatrix} 1 & 2 & -3 \\ 0 & -1 & 2 \\ -2 & 1 & 4 \\ 3 & 2 & -1 \\ 0 & 2 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 2 & -1 \\ -3 & 3 \\ 1 & 5 \end{bmatrix} \quad C = \begin{bmatrix} 1 & -2 \\ 0 & 3 \\ 2 & 4 \\ -3 & 5 \\ 4 & 6 \end{bmatrix}$$

Find: a.  $AB + 3C$       b.  $C^T A - 3B^T$       c.  $B^T B$

3. Give a geometric description of the matrix transformation  $f: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $f(\vec{u}) = A\vec{u}$ .

$$a. A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad b. A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

4. Find the reduced row echelon form of the given matrices.

$$a. A = \begin{bmatrix} 1 & 1 & 5 & 3 \\ 2 & -2 & -2 & -1 \\ -3 & 1 & -3 & 2 \end{bmatrix} \quad b. B = \begin{bmatrix} 1 & 1 & -1 \\ 3 & 4 & -1 \\ 5 & 6 & -3 \\ -2 & -2 & 2 \end{bmatrix}$$

5. Find a matrix of the form  $\begin{bmatrix} I_r & O_{rn-r} \\ O_{m-r,r} & O_{m-rn-r} \end{bmatrix}$  that is equivalent to  $\begin{bmatrix} 1 & 2 & 3 & -1 \\ 1 & 0 & 2 & 3 \\ 3 & 4 & 8 & 1 \end{bmatrix}$ .

6. Solve the given linear systems by Gauss-Jordan reduction

a.  $3x + y + 3z = 0$

$-2x + 2y - 4z = 0$

$2x - 3y + 5z = 0$

b.  $x + y + z = 1$

$x + y - 2z = 3$

$2x + y + z = 2$

c.  $x + y + 2z + 3w = 13$

$x - 2y + z + w = 8$

$3x + y + z - w = 1$

7. Find the inverse of the given matrix, if it exists.

a.  $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

b.  $\begin{bmatrix} 3 & 1 & 2 \\ 2 & 1 & 2 \\ 1 & 2 & 2 \end{bmatrix}$

c.  $\begin{bmatrix} 1 & 2 & -3 & 1 \\ -1 & 3 & -3 & -2 \\ 2 & 0 & 1 & 5 \\ 3 & 1 & -2 & 5 \end{bmatrix}$

8. Compute the following determinants via reduction to triangular form, or by citing a particular theorem or corollary.

a.  $\begin{vmatrix} 3 & 0 & 0 \\ -8 & 5 & 0 \\ 8 & -3 & -2 \end{vmatrix}$

b.  $\begin{vmatrix} -1 & 2 & 3 & -4 \\ 5 & 0 & 4 & 3 \\ -1 & 2 & 3 & -4 \\ 3 & 4 & 0 & 5 \end{vmatrix}$

c.  $\begin{vmatrix} 1 & -2 & 3 \\ -2 & 3 & 1 \\ 0 & 1 & 0 \end{vmatrix}$

9. If  $\begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = 3$  find  $\begin{vmatrix} -5a_1 & -5a_2 & -5a_3 \\ b_1 & b_2 & b_3 \\ -3b_1 + c_1 & -3b_2 + c_2 & -3b_3 + c_3 \end{vmatrix}$ .

10. Let  $A = \begin{bmatrix} -2 & 4 & 0 \\ 3 & -1 & 4 \\ 2 & 0 & -1 \end{bmatrix}$ . Find: a.  $\text{adj}(A)$       b.  $A(\text{adj } A)$       c.  $\det(A)$

11. Prove that if  $AB = AC$  and  $A$  is nonsingular, then  $B = C$ .

12. Let  $A = \begin{bmatrix} 2 & -3 & 1 \\ 5 & 4 & 0 \\ 3 & -2 & -4 \end{bmatrix}$ . Find symmetric matrix  $S$  and skew symmetric matrix  $K$  such

that  $A = S + K$ . (Hint: Recall that  $A + A^T$  is symmetric and  $A - A^T$  is skew symmetric.)

13. Let  $f : R^n \rightarrow R^m$  be a matrix transformation defined by  $f(\vec{u}) = A\vec{u}$  where  $A$  is an  $m \times n$  matrix. Show that  $f(c\vec{u} + d\vec{v}) = cf(\vec{u}) + df(\vec{v})$  for any  $\vec{u}$  and  $\vec{v}$  in  $R^n$  and any real numbers  $c$  and  $d$ .

14. If  $B = PAP^{-1}$ , express  $B^2, B^3, B^4, \dots, B^k$  where  $k$  is a positive integer, in terms of  $A, P$ , and  $P^{-1}$ .

15. If  $A$  is skew symmetric and nonsingular, then  $A^{-1}$  is also skew symmetric.

16. If  $A$  is an  $n \times n$  matrix, then  $A$  is called idempotent, if  $A^2 = A$ . Show that if  $A$  is idempotent, then  $A^T$  is also idempotent.

17. Show that if  $\vec{u}$  and  $\vec{v}$  are solutions to the linear system  $A\vec{x} = \vec{b}$ , then  $\vec{u} - \vec{v}$  is a solution to the associated homogeneous system  $A\vec{x} = \vec{0}$ .

18. Construct a linear system of equations to determine a quadratic polynomial  $p(x) = ax^2 + bx + c$  that satisfies the conditions  $p(0) = f(0)$ ,  $p'(0) = f'(0)$ , and  $p''(0) = f''(0)$ , where  $f(x) = e^{-3x}$ .